



Based on the high performance features of the SiRF StarIII low power single chipset Cold/Warm/Hot start time: 42/38/1 sec. at open sky and stationary environments

Very high sensitivity (tracking sensitivity: -159 dBm)

RF Metal Shield for best performance in noisy environments

TTL level serial port for GPS communications interface

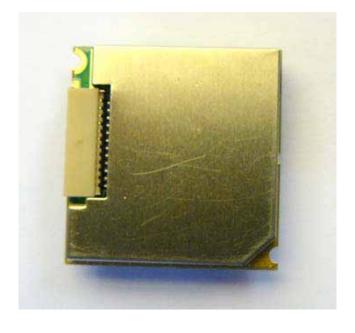
Protocol: NMEA-0183/SiRF Binary (default NMEA)

Baud Rate: 4800, 9600, 19200, 38400 or 57600 bps (default 9600)

Secure SMD PCB mounting method

Features

- SiRF Star III chipset
- Low Power: Under 60mW at full power / 46mW tracking power
- 3.0V to 3.6V operation
- High sensitivity for indoor fixes
- Support 20-channel GPS
- Real-time navigation for location-based services
- Multi-standard support: 3G PP,3GPP2,PDC,iDEN and TIA-916
- Multi-mode: Mobile centric to network cenPtric
- Interface: 2 UARTs& 1 GPIO
- RoHS Compliant
- On Board Capacitor (0.08F) for RT C, Over 30 minutes back-up power
- Mini outline: 29 X 26 X 8.4 mm (With Patch Antenna)

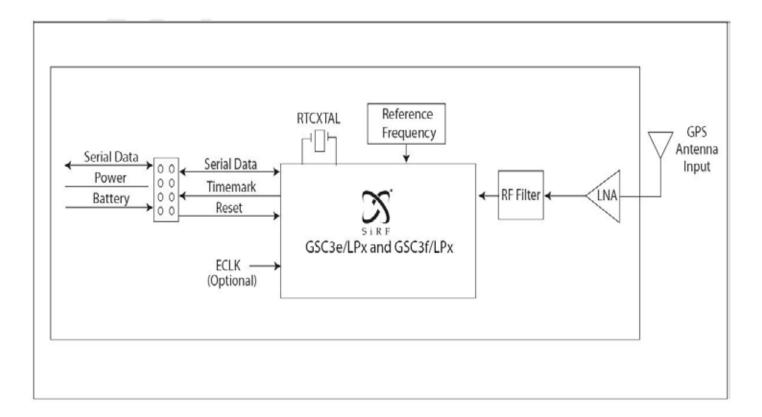








Block Diagram



Operating conditions

Parameter	Min.	Max.	Unit
VRTC	3.3	4.2	DCV
VIN	2.85	3.6	DCV
BOOTSEL	2.7	3.6	DCV
Temperature			
-	-10°	C ~ 60°C (14°F ~ 140°F)	
operating storage		C ~ 60°C (14°F ~ 140°F) C ~ 70°C (-4°F ~ 158°F)	





GPS Specification

Electrical Characteristic			
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GPS Chipset	SiRF Star III		
Frequency	L1, 1575.42 MHz		
C/A Code	1.023 MHz chip rate		
Channels	20 channel all-in-view tracking		
Accuracy			
Position Horizontal	10 meters, 2D RMS		
	1-5 meters 2D RMS, WAAS corrected		
Velocity	0.1m/sec		
Time	1 micro-second synchronized to GPS time		
Datum			
Datum	Default: WGS-84		
Acquisition Rate			
Hot start	Hot start 1 sec., average		
Warm start	start 38 sec., average		
Cold start	t 42 sec., average		
Reacquisition	Reacquisition 0.1 sec. average		
Protocol			
GPS Protocol	GPS Protocol Default: NMEA 0183 (Secondary: SiRF binary)		
GPS Output format	put format GGA(1sec), GSA(1sec), GSV(5sec), RMC(1sec), GLL, VTG is optional		
Dynamic Condition			
Altitude Limit			
Velocity Limit	Velocity Limit 515 meters/sec. (1,000 knots) max.		
Jerk Limit	Jerk Limit 20 m/sec**3		
Acceleration Limit Less than 4g			

Operating Modes

Normal Power	Entire chip enable (normal operation)		
Clock only	The RF section PLL and receiver chain are disabled. All other circuits are powered. This mode is used during low power operations such as TricklePower or Advanced Power Management. It allows the GSC3e(f)/LPx to save power by shutting down portions of the RF section while it is idle and the SiRFstarIII core and ARM are still performing.		
Stand-by	The RF section is disabled. The digital section clocks are idle. The RTC and battery back up sections are powered. This mode allows the GSC3e(f)/LPx to minimize power consumption while the chip is in an idle period such as during a power management cycle.		
Hibernate	All circuits except the RTC and battery back-up RAM are disabled. Can wake-up at a preset time or by external interrupt Vin On-Off. This is additional function to battery back up mode.		





GPM-210 Pin Function

No.	Pin Name	Pin Type	Pin description
1	BOOTSEL	Input	Module boot mode select (leave it open normally)
2	GPIO1	Output	LED Indicator (Acquisition :one flash per second / Tracking: Always ON)
3	TX0	Output	Serial message output port for channel 0
4	RX0	Input	Serial receive port for channel 0
5	TX1	Output	Serial message output port for channel 1 (leave it open normally)
6	RX1	Input	Serial receive port for channel 1 (leave it open normally)
7	RESET	Input	Reset input (leave it open normally)
8	WAKE UP	Input	Reserved
9	TIME MARK	Output	Reserved
10	VRTC	Power	RTC power intput
11	VIN	Power	VDD power input
12	GND	GND	Common ground

GPM-210 Dimension

